

1

Introduction

'Remote sensing' is, broadly but logically speaking, the collection of information about an object without making physical contact with it. (The term was coined by Evelyn Pruitt of the US Office of Naval Research in the 1950s.) This is a simple definition, but too vague to be really useful (Campbell 2008), so for the purpose of this book we restrict it by confining our attention to the Earth's surface and atmosphere, viewed from above using electromagnetic radiation. This narrower definition excludes such techniques as seismic, geomagnetic and sonar investigations, as well as (for example) medical and planetary imaging, all of which could otherwise reasonably be described as remote sensing, but it does include a broad and reasonably coherent set of techniques, nowadays often described by the alternative name of *Earth observation*. These techniques, which now have a huge range of applications in the 'civilian' sphere as well as their obvious military uses, make use of information impressed in some way on electromagnetic radiation ranging from ultraviolet to radio frequencies.

One important casualty of our restricted definition of remote sensing is the use of spaceborne methods of measuring the Earth's gravitational field. Although observations from artificial Earth satellites have been used since the 1970s to measure the Earth's gravity, our current (at the time of writing, in 2012) ability in this regard is a remarkable indication of the level of space technology. This is the GRACE (Gravity Recovery and Climate Experiment) mission, launched in 2002. Two satellites, each with a mass of around half a tonne, follow the same orbit 500 km above the Earth's surface. They are approximately 220 km apart, and the distance between them is constantly monitored with an accuracy of 10 μm . This distance changes as the satellites cross regions of different gravitational field strength. The GRACE system is sensitive enough to respond to changes in groundwater in a large river basin. Data from the GRACE mission are described in Chapter 8.

1.1

A short history of remote sensing

The origins of remote sensing can plausibly be traced back to the fourth century BC and Aristotle's *camera obscura* (or, at least, the instrument described by Aristotle in his *Problems* but perhaps known even earlier). Although significant developments in the



Figure 1.1. ‘Nadar raising Photography to the level of Art’. Lithograph by Honoré Daumier, 1863. (Source: Brooklyn Museum, via Wikipedia. [http://en.wikipedia.org/wiki/Nadar_\(photographer\)](http://en.wikipedia.org/wiki/Nadar_(photographer)))

theory of optics began to be made in the seventeenth century, and glass lenses were known much earlier than this, the first real advance towards our modern conception of remote sensing came in the first half of the nineteenth century with the invention of photography. For the first time, it became possible to record an image permanently and objectively. Also during the nineteenth century, forms of electromagnetic radiation were discovered beyond the visible part of the spectrum – infrared radiation by Herschel, ultraviolet by Ritter, and radio waves by Hertz – and in 1863 Maxwell developed the electromagnetic theory on which so much of our understanding of these phenomena depends.

Airborne photography followed almost immediately on the discovery of the photographic method. The first aerial photograph, unfortunately no longer in existence, was probably made in 1858 by Gaspard-Félix Tournachon, from a balloon at an altitude of about 80 m. Tournachon, born in 1820, used the pseudonym ‘Nadar’ and was one of the earliest developers of photography as art (Figure 1.1). He was also the inventor of the crowd control barrier. Kites were also soon used, and by 1890 the usefulness of aerial photography was so far recognised that Arthur Batut had published a textbook on the subject (Batut 1890) (Figure 1.2).

1.1 A short history of remote sensing



Figure 1.2. Labruguière, photographed from a kite by Arthur Batut in 1889. (Source: Wikipedia. http://en.wikipedia.org/wiki/Arthur_Batut)

The next step towards what we now recognise as remote sensing was taken with the development of practicable aeroplanes in the early twentieth century. Again, the potential applications were quickly recognised and aerial photographs were recorded from aeroplanes from 1909. Airborne photography was used during the First World War for military reconnaissance, and during the period between the two World Wars civilian uses of this technique began to be developed, notably in cartography, geology, agriculture and forestry. Cameras, film and aircraft underwent significant improvements, and stereographic mapping attained an advanced state of development. The modern descendants of these applications are discussed in Chapter 5. Also during this period, John Logie Baird, the inventor of television, performed early work on the development of airborne scanning systems capable of transmitting images to the ground. This work (its modern developments are discussed in Chapter 6) was highly confidential, having been carried out on behalf of the French Air Ministry. It was ended by the war and forgotten about until 1985 (Burns 2000).

The Second World War brought substantial developments to remote sensing. Photographic reconnaissance reached a high state of development – the German invasion of Britain, planned for September 1940, was forestalled by the observation of concentrations of ships along the English Channel. Infrared-sensitive instruments and radar systems were developed. In particular, the Plan Position Indicator used by night bombers was an imaging radar that presented the operator with a ‘map’ of the terrain, and thus represented the ancestor of the imaging radar systems discussed in Chapter 9.

By the 1950s, false-colour infrared film, originally developed for military use, was finding applications in vegetation mapping, and high resolution imaging radars were being developed. As these developments continued through the 1960s, sensors began to be placed in space. This was originally part of the programme to observe the Moon, but the advantages of applying the same techniques to observation of the Earth were soon recognised, and the first multispectral spaceborne imagery of the Earth was acquired from

Introduction

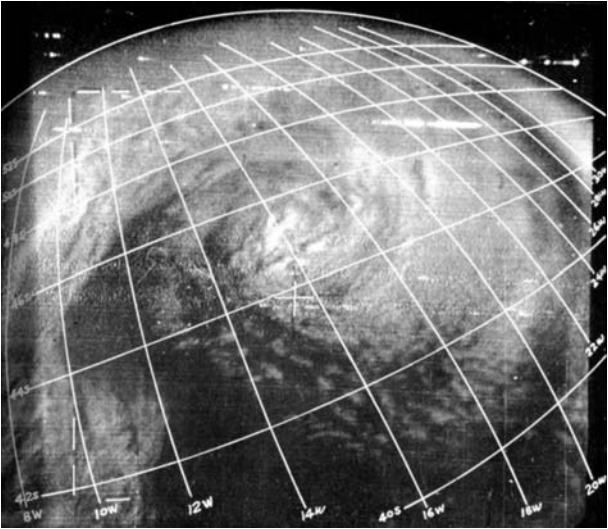


Figure 1.3. The first image transmitted to Earth electronically from a satellite. TIROS-1 (the name is an acronym for Television Infrared Observation Satellite) was the first successful weather satellite. (Source: NASA via Wikipedia. <http://en.wikipedia.org/wiki/TIROS-1>)



Figure 1.4. Extract of ERTS (Landsat-1) Multispectral Scanner image of New York, 10 October 1972.

1.2 Applications of remote sensing

Apollo 6. Although there were earlier unmanned remote sensing satellites (Figure 1.3), the opening of the modern era of spaceborne remote sensing ought probably to be dated to July 1972 with the successful operation of ERTS, the Earth Resources Technology Satellite, by the US National Aeronautics and Space Administration (NASA) (Figure 1.4). ERTS was renamed Landsat-1, and the Landsat programme is still continuing – at the time of writing (2012), Landsat-5 and Landsat-7 were both still operational.

Since the launch of ERTS in 1972, the number and diversity of spaceborne and airborne remote sensing systems has grown dramatically. A larger range of variables can be measured, and consistent and systematic datasets can be constructed for progressively longer periods of time. The explosive growth in the quantity of data being generated has been matched by growth in the availability of computing resources and the facilities for data storage and transmission. Since 2005, the availability of the *Google Earth* program has greatly increased public exposure to and use of remote sensing data.

1.2

Applications of remote sensing

The enormous growth in the availability of remotely sensed data over the last four decades has been matched by a fall in the real cost of the data. Nevertheless, it is still clear that use of the data must offer some tangible advantages to justify the cost of acquiring and analysing them. These advantages derive from a number of characteristics of remote sensing. Probably the most important of these is that data can be gathered from a large area of the Earth's surface, or a large volume of the atmosphere, in a short space of time, so that a virtually instantaneous 'snapshot' can be obtained. For example, scanners carried on geostationary meteorological satellites such as METEOSAT can acquire an image of approximately one-quarter of the Earth's surface in less than half an hour. When this aspect is combined with the fact that airborne or spaceborne systems can acquire data from locations that would be difficult (slow, expensive, dangerous, politically inconvenient ...) to measure *in situ*, the potential power of remote sensing becomes apparent. Of course, further advantages derive from the fact that most remote sensing systems generate calibrated digital data that can be fed straight into and analysed by a computer.

Remote sensing finds a very wide range of applications, naturally including the area of military reconnaissance in which many of the techniques had their origins. In the non-military sphere, most applications can loosely be categorised as 'environmental', and we can distinguish a range of environmental variables that can be measured. In the atmosphere, these include temperature, precipitation, the distribution and type of clouds, wind velocities, and the concentrations of gases such as water vapour, carbon dioxide, ozone etc. Over land surfaces, we can measure tectonic motion, topography, temperature, albedo (reflectance) and soil moisture content, and determine the nature of the land cover in considerable detail, for example by characterising the type of vegetation and its state of health or by mapping man-made features such as roads and towns. Over ocean surfaces, we can measure the temperature, topography (from which the Earth's gravitational field, as well as ocean tides and currents, can be inferred), wind velocity, wave energy spectra and colour (which is often related to biological productivity by plankton). The 'cryosphere', that part of the Earth's surface covered by snow and ice, can also be studied, giving data on the distribution, condition and dynamical behaviour of snow, sea ice, icebergs, glaciers and ice sheets.

This list of measurable variables, while not complete, is large enough to indicate that there is a correspondingly large number of disciplines to which remote sensing data can be applied. While by no means exhaustive, a list of applications could include the following disciplines: agriculture and crop monitoring, archaeology, bathymetry, cartography, civil engineering, climatology, coastal erosion, disaster monitoring and prediction, forestry, geology, geomorphology, glaciology, meteorology, oceanography, pollution monitoring, snow resources, soil characterisation, urban mapping, and water resource mapping and monitoring. It is not really possible to present a detailed cost–benefit analysis in this introduction. The development, insertion into orbit, and operation of a large remote sensing satellite costs typically a couple of billion euros. Perhaps it is sufficient to point out that the data available from remote sensing, particularly from spaceborne observations, can often not be obtained in any other way, that our current understanding of the global climate system is very largely based on spaceborne observations, and that the use of remotely sensed data for disaster warning has already saved many thousands of human lives.

As implied in Section 1.1, the era of systematic observation of the Earth from space is approaching middle age when seen from the perspective of a human lifespan. Landsat images have been collected continuously for over 40 years, radar altimeter data (which can be used to study changes in sea level, amongst many other applications) have been collected for over 20 years, and other examples can easily be found. These time-scales are long enough to form the basis of increasingly reliable measurements of change in many areas, not least of which is global change.

A systems view of remote sensing

We stated above, rather briefly, that remote sensing involves the collection of information, carried by electromagnetic radiation, about the Earth’s surface or atmosphere. Let us try to expand this statement a little.

First, where does the radiation come from? One major classification of remote sensing systems is into the passive systems, which detect naturally occurring radiation, and the active systems, which emit radiation and analyse what is sent back to them. The passive systems can be further subdivided into those that detect radiation emitted by the Sun (this radiation consists mostly of ultraviolet, visible and near-infrared radiation), and those that detect the thermal radiation that is emitted by all objects that are not at absolute zero (i.e. all objects). For objects at typical terrestrial temperatures, this thermal emission occurs mostly in the infrared part of the spectrum, at wavelengths of the order of 10 µm (the so-called thermal infrared region), although measurable quantities of radiation also occur at longer wavelengths, as far as the microwave part of the spectrum. Active systems can, in principle, use any type of electromagnetic radiation. In practice, however, they are restricted by the transparency of the Earth’s atmosphere. This is shown schematically in Figure 1.5. Chapter 4 presents a detailed discussion of the interaction of electromagnetic radiation with the atmosphere.

Figure 1.5 shows that there are three main ‘windows’ in the atmosphere. The first of these includes the visible and near-infrared (VNIR) parts of the spectrum, between wavelengths of about 0.3 µm and 3 µm, although it does also contain a number of opaque

1.3 A systems view of remote sensing

Table 1.1. A simple taxonomy of remote sensing systems, excluding sounding instruments. The numbers in parentheses refer to the chapters of this book.			
		Active systems	
		Ranging	Imaging
VNIR	Aerial photography (5) Electro-optical systems (6)	Laser profiler (8)	
TIR	TIR imager (6)		
Microwave	Passive microwave radiometer (7)	Radar altimeter (8) Ground-penetrating radar (8)	Microwave scatterometer (9) Imaging radar (9)

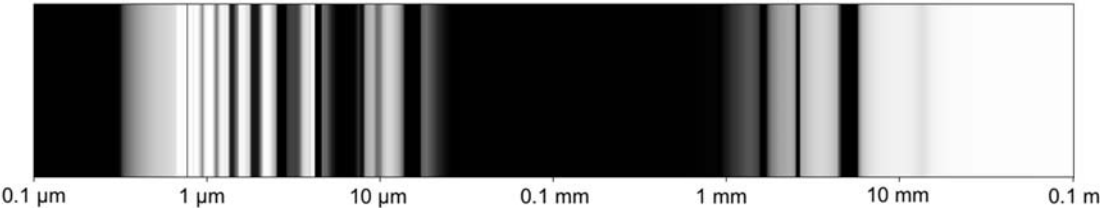


Figure 1.5. Transparency of the Earth’s atmosphere as a function of wavelength (schematic). Black regions are opaque, white regions transparent.

regions. The second is a rather narrow region between about 8 μm and 15 μm, in which is found the bulk of the thermal infrared (TIR) radiation from objects at typical terrestrial temperatures. The third more or less corresponds to the microwave region, between wavelengths of a few millimetres and a few metres. Thus we can expect that any active system designed to penetrate the Earth’s atmosphere will operate in one of these three ‘window’ regions.

Table 1.1 summarises the main types of remote sensing system on the basis of the classifications we have just outlined. Sounding instruments, intended to profile some property of the atmosphere such as its temperature or chemical composition, generally operate on the boundaries between transparency and opacity of the atmosphere.

The sensor, whether it is part of a passive or an active instrument, detects electromagnetic radiation after it has interacted with or been emitted by the ‘target’ material. In what way can this radiation contain useful information about the target? There are essentially only two variables to describe the radiation that is received: *how much* radiation is detected (we may need to qualify this with a statement about the polarisation of the radiation), and *when* does it arrive? The time-structure of the detected radiation is obviously only relevant in the case of active systems where the time-structure of the emitted radiation can be controlled. In this case it is possible to determine the distance from the sensor to the target, and this is the principle behind various ranging systems such as the laser profiler, LiDAR, radar altimeter and other types of radar system. In all other

Introduction

cases, the only information we have is the quantity of radiation received at the sensor. If the radiation arises from thermal emission, the quantity is characteristic of the temperature of the target material and its emissivity, a property that describes its efficiency at emitting thermal radiation. Otherwise (in the cases of both passive and active systems that measure reflected radiation) the amount of radiation that is received is determined by the amount illuminating the target material, and the target's reflectivity. Thus we can see that the information about a target material that is directly observable from remote sensing observations is actually rather limited: we can measure its range, its reflectivity, and a combination of its temperature and emissivity. However, these can be measured at different times, over a range of wavelengths and, sometimes, in different polarisation states, and this increase in the diversity of the variables at our disposal is responsible for the large range of indirect observables that was sketched out in Section 1.2.

The foregoing discussion has not included the effects of the Earth's atmosphere, except to point out that atmospheric opacity limits the scope for observing the Earth's surface to the main atmospheric 'windows'. In fact, as almost any electromagnetic wave propagates through the atmosphere, its characteristics will be somewhat modified. This modification may be troublesome, requiring correction, or advantageous depending on whether we are more interested in studying the Earth's surface or the atmosphere itself. In general, we can say that if the observation is made at a wavelength at which the atmosphere is opaque, the measured signal will be characteristic of the atmosphere, whereas if the atmosphere is transparent, the data will be characteristic of the surface below.

Once the data have been collected by the sensor, they must be retrieved and analysed. In many, though not all, cases, the data will form an image, by which we mean a two-dimensional representation of the two-dimensional distribution of radiation intensity. Since the second edition of this book appeared in 2001, the concepts of digital imaging and digital images have become much more generally familiar as a result of the huge increase in the popularity of digital photography and the use of *Google Earth* and similar web-based resources. The images with which we have to deal in remote sensing are normally digital, so they can conveniently be analysed by computer, and need not be confined to the visible part of the electromagnetic spectrum. For example, an image might represent the radar reflectivity in one or more frequencies or polarisation states, or the thermal emission, as well as the visible or near-infrared reflectivity. Image processing forms an integral part of remote sensing. Typically, this involves several steps. The first is to correct the image so that it has a known geometrical correspondence to the Earth's surface and a known calibration, with atmospheric propagation effects removed. At this stage, the image may also be enhanced in various ways, for example by suppressing noise, to increase its intelligibility. The major goal of image processing, however, is the extraction of useful information from the sensor data, based on the brightness values of the image (probably in a number of spectral bands, at a number of different dates, in different polarisation states etc.) and also on the spatial context. Using the analogy of a colour photograph, we can say that information can be extracted on the basis of colour, texture, shape and spatial context. In the majority of cases, it is necessary or at least desirable to 'train' the process of extracting information from the image using data from known locations. The process can therefore be seen as one of extrapolation from areas that are already known, for example on the basis of field work, to much wider areas. The

1.4 Further reading, and how to obtain data

extrapolation need not be confined to the spatial domain, however, and the analysis of time-series of images for change detection is also an important application of remote sensing.

1.4

Further reading, and how to obtain data

The field of remote sensing is now well served with textbooks, and the interested (or puzzled) reader should be able to find alternative treatments of most of the topics discussed in this book. While what follows is a personal list and makes no pretence to completeness, recent general textbooks include the fourth edition of Campbell's *Introduction to Remote Sensing* (Campbell 2008) and the sixth edition of Lillesand, Kiefer and Chipman's *Remote Sensing and Image Interpretation* (Lillesand, Kiefer and Chipman 2008), while the *SAGE Handbook of Remote Sensing* (Warner, Nellis and Foody 2009) provides exceptional breadth of treatment. Somewhat more detailed or more specialised treatments are given by, for example, the second edition of Jensen's *Remote Sensing of the Environment* (Jensen 2006), Jones and Vaughan's *Remote Sensing of Vegetation* (Jones and Vaughan 2010), Purkis and Klemas's *Remote Sensing and Global Environmental Change* (Purkis and Klemas 2011), Liang's *Quantitative Remote Sensing of Land Surfaces* (Liang 2004) and the second edition of Elachi and van Zyl's *Introduction to the Physics and Techniques of Remote Sensing* (Elachi and van Zyl 2006).

Scientific journals also represent an important source of information. Articles in the scientific literature are usually aimed at specialists, but the more general reader can often also extract a useful understanding from them, and the journals sometimes also publish review articles. In this book I have provided references to both books and journal articles. The principal English language journals in remote sensing are the *Canadian Journal of Remote Sensing*, *Computers & Geosciences*, *Geophysical Research Letters*, *IEEE Transactions on Geoscience and Remote Sensing*, the *International Journal of Remote Sensing*, *Photogrammetric Engineering and Remote Sensing*, and *Remote Sensing of Environment*.

Finally, a few remarks about the Internet may be useful. This can represent a very powerful means of obtaining up-to-date information of all sorts, for example on the operational status of a particular remote sensing satellite, or the latest results from a research group, or access to remote sensing data (indeed, some of the illustrations used in this book have been obtained in this way) or the software needed to process it. As anyone who has grappled with the Internet will know only too well, the problem is usually to locate the information one needs. The well-known search engines can be extremely helpful, as can the collections of links assembled by public-spirited individuals and organisations. The website of this book is located at www.cambridge.org/9781107004733 and it includes a collection of links to some other useful websites including online catalogues from which satellite data may be located.

A question that inevitably arises when one starts to consider obtaining satellite or other remotely sensed imagery is – what does it cost? There is no single, simple answer to this question. As a rough guide, though, one may say that the coarser the spatial resolution of the imagery the more likely it is to be freely available, and the finer the spatial resolution the more likely it is to be rather expensive, by which one might mean a thousand pounds or equivalent. As an example, imagery from a particular commercial spaceborne

instrument, having a spatial resolution of around 1 m, cost US\$10–20 per square kilometre in late 2010, while MODIS imagery, with a spatial resolution of 250–1000 m, was freely available. Images collected by the Landsat series of satellites, having spatial resolutions of 15–80 m, were also freely available at the time of writing. The trend over the last decade or so has been towards the free availability of satellite imagery.

As noted in Section 1.3, quantitative processing of spatial data is an integral part of remote sensing. Some of the mathematical principles of image processing are discussed in Chapter 11. There is of course a wide range of computer software for manipulating and processing image data, often very powerful and flexible. However, such software can also manifest some disadvantages. It may be expensive, demanding of computing resources (memory, processing power and so on), able to run only on specific computing platforms, dependent on its own specific file formats, and so on. In contrast to this approach is the existence of free software, especially when developed in an open-source environment. The website of this book has links to sources of free software for image processing and for geographic information systems (GIS), a related technology that is discussed briefly in Chapter 11. In addition, readers of this book might wish to develop their own software for carrying out image processing operations. Again, there are several suitable possibilities among programming languages. Of freely available programming languages, two of the most useful are *R* and *GNU Octave*, both available since the early 1990s. GNU Octave is designed particularly for manipulating matrices, and since images share many properties with matrices (see Chapter 11) it is particularly well suited to processing images. GNU Octave runs under most computer operating systems. The book's website has a number of Octave programs that the reader can download and use to explore some of the topics discussed in the text, and readers are encouraged to submit their own programs.