
Contents

List of Figures xv

List of Tables xix

1 Manufacturing Systems: Trends, Classification, and Behavior Patterns 1

1.1 Distributed Flexible Manufacturing Systems 2

1.1.1 DFMS Properties 4

1.1.2 DFMS Behaviour 7

1.1.3 Organizational Paradigms 8

1.1.4 Example of the Implementation of a Holonic Manufacturing System in Induction Motor Production . 10

1.1.5 A Layered Approach to DFMS Modeling 13

1.2 Manufacturing Control (MC) 14

1.2.1 Definition of Manufacturing Control 14

1.2.2 Manufacturing Control Functions 16

1.2.3 Classification of Production Scheduling 18

1.3 Scheduling and Resource Allocation 23

1.3.1 Definition 23

1.3.2 Mathematical Model for Job Shop Scheduling 24

1.4 On-line Manufacturing Control 27

1.4.1 Computational Complexity of Scheduling and Resource Allocation 28

1.5 Algorithmic Approach to Problem Solution 28

1.5.1 Greedy Heuristics 29

1.5.2 Local Search Heuristics 30

1.5.3 Off-line and On-line Algorithms 32

1.6 Conclusions 33

2	On-Line Load Balancing	35
2.1	Problem Definition	35
2.2	Known Results and Existing Approaches	36
2.2.1	The Greedy Approach	37
2.2.2	The Robin-Hood Algorithm	39
2.2.3	Tasks with Known Duration: the Assign1 Algorithm	41
2.3	A Metaheuristic Approach	43
2.4	Example	48
2.5	Experimental Results	53
2.5.1	A Multi-objective Approach in the Case of Known Task Departure Dates	57
2.6	Conclusions	62
3	Resource Levelling	65
3.1	Background and Problem Definition	65
3.2	Resource Levelling and the Minimization of the Peak and the Makespan	68
3.3	The Greedy Approach	75
3.4	The Metaheuristic Approach	78
3.4.1	Conceptual Comparison with Known Local Search Methods	79
3.4.2	How to Control the Effect of the Minimization of the Makespan and the Frequency Based Memory	82
3.5	Experimental Results	84
3.5.1	Description of the Experiments	84
3.5.2	Analysis of the Results	85
3.5.3	Lower Bounds Comparison	87
3.5.4	Comparison with Known Algorithms	90
3.6	The Extension to the Case with Arbitrary Integer Duration	93
3.7	Case Study 1	95
3.8	Case Study 2	100
3.9	Conclusions	103
4	Scheduling Jobs in Robotized Cells with Multiple Shared Resources	105
4.1	Background and Problem Definition	105
4.2	Problem Definition	107
4.3	$\mathcal{NP}$ -Completeness Result	109
4.4	The Proposed Heuristic	110
4.5	Computational Results	114
4.6	Conclusions	120

5	Tool Management on Flexible Machines	121
5.1	Background	121
5.1.1	Definition of the Generic Instance	126
5.1.2	Assumptions	126
5.2	The Binary Clustering and the KTNS Approaches	127
5.3	The Proposed Algorithms	130
5.3.1	Algorithm 1	130
5.3.2	Algorithm 2	135
5.3.3	Algorithm 3	141
5.3.4	Algorithm 4	148
5.4	Computational Analysis	153
5.4.1	Comparison with Tang and Denardo	153
5.4.2	Comparison with Crama <i>et al.</i>	155
5.4.3	Comparison Among the Proposed Algorithms	163
5.5	Conclusions	168
Appendix A		171
Appendix B		193
Glossary		199
References		201
Index		215